



Flowserve Corporation Flow Control Division www.flowserve.com

1350 N. Mountain Springs Parkway Springville, Utah 84663 Phone: 801 489 8611

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Automax XL90 High Performance Positioner



Introduction

The Automax XL90 positioner provides outstanding control for a wide range of valves and dampers. The XL90's twostage relay provides fast, sensitive response characteristics to meet demanding control objectives. It may be used with 3-15 psi pneumatic control signals (as shown) or fitted with an I/P transducer for 4-20 mA signals. The XL90 is available with many options including position feedback limit switches, 4-20 mA position feedback transmitter, and our UltraDome visual position indicator.

Applications

Automax XL90 positioners may be used to control quarter-turn control valves such as eccentric plug, butterfly, segmented ball, standard ball, and plug valves. The XL90's sensitive two-stage relay also makes it ideal for precise damper control applications. Specify the XL90 whenever valve rotation sensitivity is critical.

The XL90 may be installed on any quarter-turn valve actuator conforming to the NAMUR standard for accessory mounting bolt pattern and pinion height without a coupler. This reduces deadband and is less expensive. Contact your Flowserve distributor or representative for information about mounting the XL90 on non-NAMUR actuators.

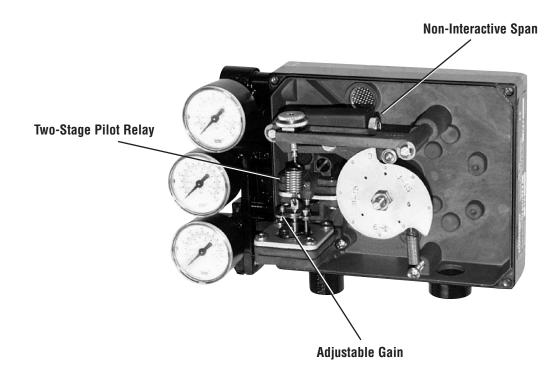
The XL90 housing is constructed from durable die-cast aluminum. The housing is anodized for internal corrosion resistance, then coated with epoxy powder for external resistance to harsh chemicals.

FCD AXENPS0029-01 10/05 (Replaces Auto-29) Page: 1 of 6





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Features

- 1. **Two-Stage Pilot Relay** provides fast, sensitive response characteristics for precise control of critical control valves and dampers.
- 2. Non-interactive Span Adjustment reduces calibration time.
- 3. Adjustable Gain allows positioner sensitivity adjustment for a wide range of valve/actuator applications.
- 4. **Corrosion Resistant Materials.** All exposed parts are either stainless steel or epoxy powder coated anodized aluminum to permit use in corrosive environments.
- 5. Optional **UltraDome Visual Position Indicator** provides adjustable, high-contrast, full-angle viewing of valve position.
- 6. **Field Upgradable.** The XL90 is field-upgradable to a number of electro-pneumatic options without removing the cover. Limit switches or a 4-20 mA position transmitter may be installed with basic tools.
- 7. **Vibration Resistant.** High natural frequency and pneumatic dampening make the XL90 unaffected by vibrations with accelerations up to 2 G's and frequencies to 500 Hz.





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Materials of Construction:

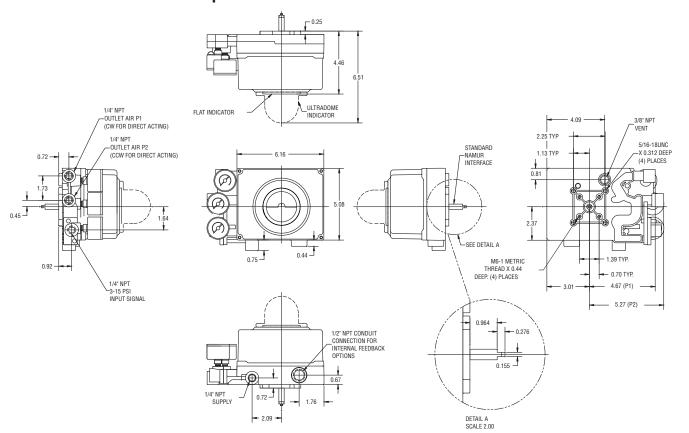
Part of Assembly	Materials		
Housing	Anodized Aluminum with Epoxy Powder Paint		
Screen/Retainer	Stainless Steel		
Cover	Anodized Aluminum with Epoxy Powder Paint		
Lens/UltraDome	Polycarbonate		
Shaft	Stainless Steel		
Bearings	Thermoplastic Alloy		
Cam	Stainless Steel		
Cam Follower Bearing	Hardened Steel		
Span Arm	Anodized Aluminum		
Span Arm Screws	Stainless Steel		
Zero Arm	Anodized Aluminum		
Relay Assembly	Anodized Aluminum and Stainless Steel		
All Fasteners	Stainless Steel		
O-rings*	Buna-N		
Diaphragms*	Buna-N		
Feedback and Cam Springs	Stainless Steel		
Shaft Snap Rings	Stainless Steel		
Posts and E-Clips	Stainless Steel		

*Ext. Temp. Models utilized fluorosilicone diaphragms and dynamic O-rings.

Specifications:

Parameter	Units	P/P Value	I/P Value
Resolution	% Full Scale	0.1	0.1
Dead Band	% Full Scale	0.1	0.1
Repeatability	% Full Scale	0.1	0.1
Hysteresis	% Full Scale	0.5	0.5
Linearity	% Full Scale	1	1
Adjustable Open Loop Gain	psi/psi @ 60 psi	400 to 1100:1	400 to 1100:1
Supply Pressure Effect	% Full Scale	0.2	0.2
Supply Pressure Range	PSIG	30 to 150	30 to 150
Steady State Air Consumption	SCFM @ 60 psi	0.38	0.45
Maximum Flow Capacity	SCFM @ 60 psi	16.5	16.5
Ambient Temp. Range - Standard	Degrees F	-20 to 185	-20 to 180
Ambient Temp. Range - Extended	Degrees F	-50 to 250	-40 to 180
Input Signal	PSIG/mA	3 to 15	4 to 20
Pneumatic Connections	Inch NPT	1/4	1/4
Conduit Connection	Inch NPT	1/2	1/2
Net Weight	lbs.	3.5	6

Dimensions: Pneumatic Input Models

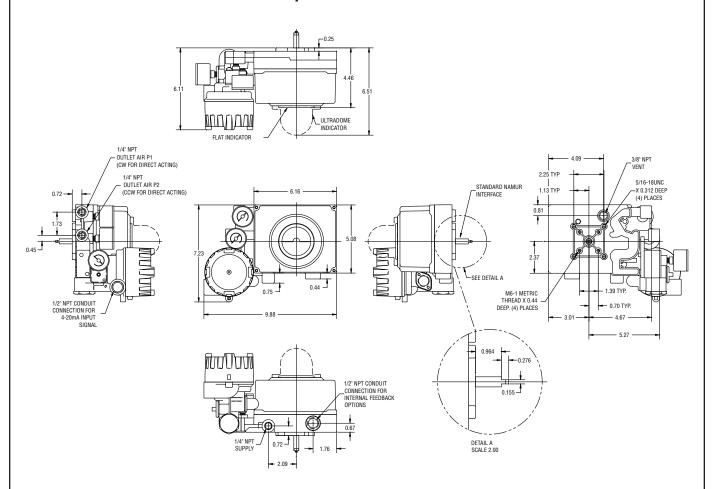






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Dimensions: Electro-Pneumatic Input Models







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POSITIONER OPERATION

The positioner schematic (Figure 1) shows an XL90 Series positioner connected for double-acting service on a rotary rack-and-pinion actuator. Tension on the feedback spring provides feedback to the positioner, which varies as the stem position changes. The spring-loading force is applied through the feedback linkage and cam to the positioner's input capsule.

Instrument signal pressure is applied between the diaphragms in the input capsule. Therefore, the input capsule serves as a force-balance member, matching the valve stem position (as measured by tension on the feedback spring) to the instrument signal.

When the opposing forces balance exactly, the system will be in equilibrium and the stem will be in the exact position called for by the instrument signal. If the opposing forces are not in balance, the input capsule will move up or down and, by means of the pilot-valves, will change the output pressures, moving the stem until the tension on the feedback spring exactly opposes the instrument signal pressure.

The sequence of operation is as follows: An increase in instrument signal pressure forces the input capsule downward. Displacement of the capsule in turn moves the flapper away from the detecting nozzle. This allows a larger flow rate through the nozzle, decreasing the pressure exerted on the top of the pilot valve capsule.

Supply air biases the pilot-valve in an upward direction. As the capsule moves up, it will close the exhaust seat of the upper pilot poppet and open the supply seat, which applies increased air pressure to the bottom cylinder port. At the same time, the pilot-valve capsule will open the exhaust seat for the lower pilot poppet; thus, decreasing pressure to the top cylinder port.

This difference in pressure will drive the piston outward, rotate the pinion and stretch the feedback spring until the spring tension exactly opposes the force resulting from the instrument signal pressure. At this point, the flapper will be moved toward the detecting nozzle to restore the pressure above the pilot-valve capsule to its equilibrium value. As a force-balanced condition is approached, the pilot-valve capsule will be forced back to a neutral position where the pilots are neither supplying air to, nor exhausting air from, their respective sides of the piston.

A decrease in instrument signal pressure reverses the described actions and causes a proportional inward movement of actuator pistons and a reversal in pinion direction.

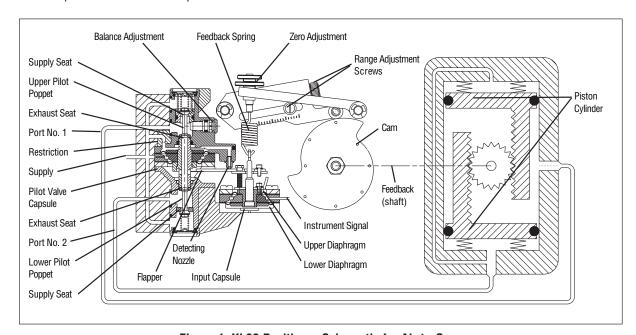


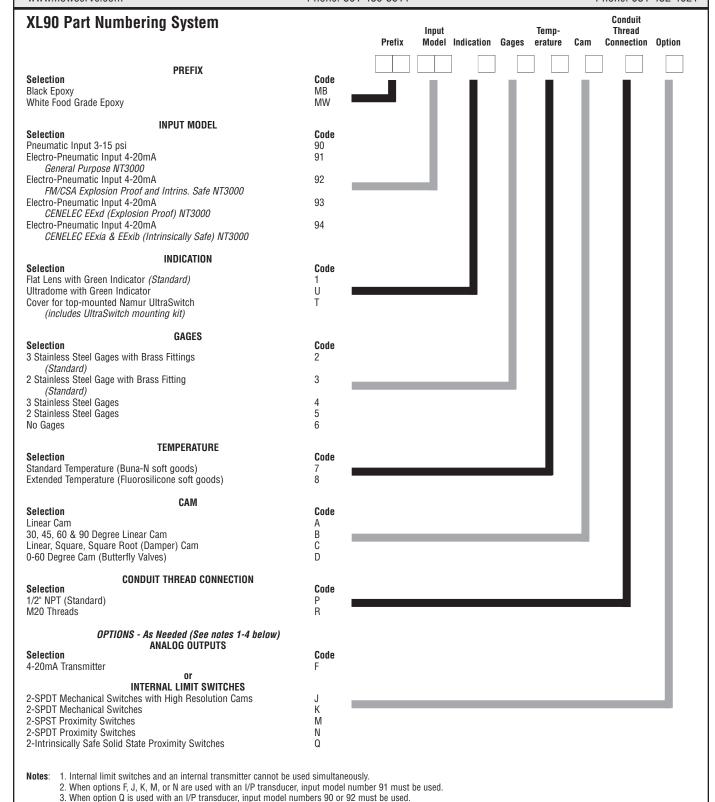
Figure 1: XL90 Positioner Schematic for Air-to-Open



Automax Valve Automation Systems

Product Specification

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4. Internal limit switches or an internal transmitter cannot be used in an explosion proof environment. As an alternative, the explosion proof UltraSwitch may be mounted

on top of the positioner. (Use option T.)